

ORTHOGONAL TRAJECTORIES

If a curve intersects every member of a given family of curves at 90° , it is called orthogonal trajectory. If the angle is not 90° , it is called an oblique trajectory.

Methodology

Cartesian equ.

1. Differentiate w.r. to x and find $\frac{dy}{dx}$.
2. Eliminate the parameter
3. Replace $\frac{dy}{dx}$ by $-\frac{dx}{dy}$.
4. Integrate. You get the solution

1 Find the orthogonal trajectories of family of curves $y = ax^2$, a being a parameter.

Soln

Given, $y = ax^2$ — (1)

$$\Rightarrow \frac{dy}{dx} = 2ax = 2x \times a$$

$$= 2x \times \frac{y}{x^2} \quad \left[\because y = ax^2 \text{ from (1)} \right]$$

$$\Rightarrow \frac{dy}{dx} = \frac{2y}{x}$$

Replace $\frac{dy}{dx}$ by $-\frac{dx}{dy}$ in the above

equation.

$$\Rightarrow -\frac{dx}{dy} = \frac{2y}{x} \Rightarrow x dx = -2y dy$$

$$\Rightarrow x dx + 2y dy = 0$$

Integrating, we get

$$\frac{x^2}{2} + y^2 = \frac{C}{2}$$

$$\Rightarrow x^2 + 2y^2 = C$$

This is the required orthogonal trajectories of the given eqn.

2. Find the orthogonal trajectories of family of curves $3xy = x^3 - a^3$, a being parameter of the family.

Soln Given $3xy = x^3 - a^3$

Diff w.r. to x , we get

$$3 \left(x \frac{dy}{dx} + y \right) = 3x^2$$

$$\Rightarrow x \frac{dy}{dx} + y = x^2$$

Replacing $\frac{dy}{dx}$ by $-\frac{dx}{dy}$, we get

$$-x \frac{dx}{dy} + y = x^2$$

$$\Rightarrow x \frac{dx}{dy} - y = -x^2$$

$$\Rightarrow x \frac{dx}{dy} + x^2 = y$$

Put $x^2 = z$
 $\Rightarrow 2x \frac{dx}{dy} = \frac{dz}{dy}$

$$\Rightarrow \frac{1}{2} \frac{dz}{dy} + z = y$$

$$\Rightarrow \frac{dz}{dy} + 2z = 2y \quad \text{which is a linear}$$

diff. eqn.

$$I.F = e^{\int 2 dy} = e^{2y}$$

∴ Its soln. is given by

$$z \times \partial F = \int Q \cdot x \text{ IF } dy$$

$$\Rightarrow z e^{2y} = \int 2y e^{2y} dy + k$$

$$\Rightarrow z e^{2y} = 2y \int e^{2y} dy - 2 \int \left[\frac{dy}{dy} \int e^{2y} dy \right] dy$$

$$= 2y \cdot \frac{e^{2y}}{2} - 2 \int \frac{e^{2y}}{2} dy + k$$

$$\Rightarrow z e^{2y} = y e^{2y} - \frac{e^{2y}}{2} + k$$

$$\Rightarrow z = y - \frac{1}{2} + k e^{-2y}$$

This is the required orthogonal trajectory

Q

Find the orthogonal trajectory of

$$x^2 + y^2 = 2ax.$$

$$\therefore x^2 + y^2 = 2ax \quad \text{--- (1)}$$

$$\Rightarrow 2x + 2y \frac{dy}{dx} = 2a$$

$$\Rightarrow x + y \frac{dy}{dx} = a \quad \text{--- (2)}$$

$$\text{From (1)} \quad a = \frac{x^2 + y^2}{2x}$$

so (2) becomes

$$x + y \frac{dy}{dx} = \frac{x^2 + y^2}{2x}$$

Replace $\frac{dy}{dx}$ by $-\frac{dx}{dy}$ in the above eqn.

$$\Rightarrow x - y \frac{dx}{dy} = \frac{x^2 + y^2}{2x}$$

$$\Rightarrow x - \frac{x^2 + y^2}{2x} = y \frac{dx}{dy}$$

$$\Rightarrow \frac{x^2 - y^2}{2x} = y \frac{dx}{dy}$$

$$\Rightarrow \frac{dy}{dx} = \frac{2xy}{x^2 - y^2}$$

which is a homogeneous eqn.

$$\text{Put } y = vx \Rightarrow \frac{dy}{dx} = v + x \frac{dv}{dx}$$

$$\therefore v + x \frac{dv}{dx} = \frac{2x \cdot vx}{x^2 - v^2 x^2} = \frac{2v}{1 - v^2}$$

$$\Rightarrow x \frac{dv}{dx} = \frac{2v}{1 - v^2} - v = \frac{v + v^3}{1 - v^2} = \frac{v(1 + v^2)}{1 - v^2}$$

$$\Rightarrow \frac{(1 - v^2)}{v(1 + v^2)} dv = \frac{dx}{x} \Rightarrow \frac{dx}{x} = \frac{dv}{v} - \frac{2v dv}{1 + v^2}$$

integrating, $\Rightarrow \log x = \log v - \log(1 + v^2) + \log k$

$$\Rightarrow x(1 + v^2) = vk \Rightarrow x \left(1 + \frac{y^2}{x^2} \right) = \frac{y}{x} k$$

$$\Rightarrow \frac{1}{x} (x^2 + y^2) = \frac{y}{x} k \Rightarrow \boxed{x^2 + y^2 = ky}$$

This is the required o.t. \Rightarrow