

Orthogonal Curvilinear coordinates: —

In previous lecture note we have discussed the metric coefficient g_{ij} is given by

$$g_{ij} = \vec{a}_i \cdot \vec{a}_j, \quad \text{--- (1)}$$

which is symmetric

For orthogonal curvilinear coordinates $g_{ij} = \vec{a}_i \cdot \vec{a}_j = 0$
for $i \neq j$

ie. for 2D case $g_{12} = 0, g_{21} = 0 \dots$
 \downarrow
 $(i, j = 1, 2)$

Let us write ds^2 for 3D case

$$ds^2 = g_{11} (du_1)^2 + g_{22} (du_2)^2 + g_{33} (du_3)^2 \quad \text{--- (2)}$$

We can write a matrix $[g]$ for an orthogonal coordinate system as

$$[g] \equiv \begin{bmatrix} g_{11} & 0 & 0 \\ 0 & g_{22} & 0 \\ 0 & 0 & g_{33} \end{bmatrix}$$

Let us define (from 2) $ds_1 = \sqrt{g_{11}} du_1$

$$ds_2 = \sqrt{g_{22}} du_2$$

$$ds_3 = \sqrt{g_{33}} du_3$$

$$\text{or } ds_1 = h_1 du_1, \quad ds_2 = h_2 du_2 \quad \text{and} \quad ds_3 = h_3 du_3$$

where h_1, h_2 and h_3 are scale factors

Now we can write (2) as

$$ds^2 = h_1^2 du_1^2 + h_2^2 du_2^2 + h_3^2 du_3^2 \quad \text{--- (3)}$$

Note: for cartesian coordinate system -

$$g_{11} = g_{22} = g_{33} = 1$$

$$\text{and } ds^2 = du_1^2 + du_2^2 + du_3^2$$

Since we know that $h_1 = \sqrt{g_{11}}$, $h_2 = \sqrt{g_{22}}$ & $h_3 = \sqrt{g_{33}}$,
we can calculate h_1, h_2 & h_3 using expression for g_{ii}

Next we show how to calculate h_i :

We can write ds^2 as

$$ds^2 = \sum_{k=1}^3 dx_k dx_k$$

$$\text{or } ds^2 = \sum_{k=1}^3 \left[\left(\sum_{i=1}^3 \frac{\partial x_k}{\partial u_i} du_i \right) \left(\sum_{j=1}^3 \frac{\partial x_k}{\partial u_j} du_j \right) \right]$$

$$\text{or } ds^2 = \sum_{i=1}^3 \sum_{j=1}^3 \left(\sum_{k=1}^3 \frac{\partial x_k}{\partial u_i} \frac{\partial x_k}{\partial u_j} \right) du_i du_j \quad \text{--- (4)}$$

~~Since~~ In previous lecture notes we have seen that

$$ds^2 = \sum_{i=1}^3 \sum_{j=1}^3 g_{ij} du_i du_j$$

∴ Thus from (4)

$$g_{ij} = \sum_{k=1}^3 \frac{\partial x_k}{\partial u_i} \frac{\partial x_k}{\partial u_j}$$

or for orthogonal curvilinear coordinates

$$g_{ii} = \sum_{k=1}^3 \left(\frac{\partial x_k}{\partial u_i} \right)^2 \quad \text{--- (5)}$$